

Ковчиг проблем:

$$x^{(n)} + a_{n-1}(t)x^{(n-1)} + \dots + a_1(t)x' + a_0(t)x = f(t)$$

Услови: $x(t_0) = x_0$
 $x'(t_0) = x_1$
 $x''(t_0) = x_2$
 \vdots
 $x^{(n-1)}(t_0) = x_{n-1}$

} n услова (јна)

↳ у истом тренутку

није К-П:

- $x(0) = 1, x(1) = 2$
- $x'(0) = 0, x(1) = 2$

1) Решити ковачиг проблем

^{3. step}
 $x''' + x'' = 0$

$$\begin{aligned} x(0) &= 1 \\ x'(0) &= 0 \\ x''(0) &= 1 \end{aligned}$$

$$\lambda^3 + \lambda^2 = 0$$

$$\lambda^2(\lambda + 1) = 0$$

$$\hookrightarrow \underbrace{0, 0, -1}_{1, t} \quad e^{-t}$$

OP: $x(t) = c_1 + c_2 t + c_3 e^{-t}, c_i \in \mathbb{R}$

$$x(0) = c_1 + c_3 = 1$$

$$x'(t) = c_2 - c_3 e^{-t}$$

$$x'(0) = c_2 - c_3 = 0$$

$$x''(t) = c_3 e^{-t}$$

$$x''(0) = c_3 = 1$$

$$\left. \begin{aligned} c_2 = c_3 = 1 \\ c_1 = 0 \end{aligned} \right\} x_k(t) = t + e^{-t}$$

неоднородни случај: $f \neq 0$

$$x^{(n)} + a_{n-1}x^{(n-1)} + \dots + a_1x' + a_0x = f(t)$$

у неоднородном случају: $f(t) = e^{\alpha t} \cdot (P_n(t) \cos \beta t + Q_m(t) \sin \beta t)$

$\alpha, \beta \in \mathbb{R}$
 $\alpha \pm i\beta$ - комплексни бројеви
 као реална коракта. је

P_n - n -тн. ст. и
 Q_m - m -тн. ст. и

$$x_p(t) = t^k \cdot e^{\alpha t} \cdot (R_k(t) \cos \beta t + T_k(t) \sin \beta t)$$

R_k, T_k - k -тн. ст. и
 $k = \max\{u, v\}$

2) a) $x''' - x'' + x' - x = t^2 + t$

OP: $x(t) = x_h(t) + x_p(t)$

$$x_h(t) = c_1 e^t + c_2 \cos t + c_3 \sin t, c_1, c_2, c_3 \in \mathbb{R}$$

$$\lambda^3 - \lambda^2 + \lambda - 1 = 0$$

$$(\lambda - 1)(\lambda^2 + 1) = 0$$

$$\hookrightarrow \underline{1, \pm i}$$

$$x_p(t) = ?$$

$$\alpha = 0 \quad (e^{0t} = 1)$$

$$\beta = 0 \quad (\cos 0t = 1, \sin 0t = 0)$$

$$\begin{aligned} P_n(t) = t + t^2 \rightarrow n=2 \\ Q_m(t) = \text{polynomial} \quad (m=0) \end{aligned} \left. \vphantom{\begin{aligned} P_n(t) = t + t^2 \\ Q_m(t) = \text{polynomial} \end{aligned}} \right\} K = m \times \{1, 0\} = 2.$$

$$\delta = ? \quad \alpha \pm i\beta = 0 \pm i0 = 0 \notin \{1, \pm i\} \Rightarrow \delta = 0$$

$$x_p(t) = t^0 \cdot e^{0t} \cdot (R_2(t) \cdot \cos 0t + T_2(t) \cdot \sin 0t) = R_2(t) = at^2 + bt + c$$

$$x_p''' - x_p'' + x_p' - x_p = t + t^2 \leftarrow$$

$$x_p' = 2at + b$$

$$x_p'' = 2a$$

$$x_p''' = 0$$

$$0 - 2a + 2at + b - at^2 - bt - c = t + t^2$$

$$\left. \begin{aligned} -a &= 1 \\ 2a - b &= 1 \\ -2a + b - c &= 0 \end{aligned} \right\} \begin{aligned} a &= -1 \\ b &= -3 \\ c &= -1 \end{aligned}$$

$$x_p(t) = -t^2 - 3t - 1$$

$$b) \quad x'''' - x'' + x' - x = \cos t + e^{2t} \rightarrow \text{kuže y opř. odměry}$$

$$1, \pm 2$$

$$f_1(t) = \cos t \rightarrow x_{p1}(t)$$

$$f_2(t) = e^{2t} \rightarrow x_{p2}(t)$$

$$OP: x(t) = x_H(t) + x_{p1}(t) + x_{p2}(t)$$

$$x_H(t) = c_1 e^t + c_2 \cos t + c_3 \sin t, c_i \in \mathbb{R}$$

$$\rightarrow \text{sum.} \quad L(x) = f_1(t) + f_2(t)$$

$$L(x_{p1}) = f_1(t)$$

$$L(x_{p2}) = f_2(t)$$

$$L(x_{p1} + x_{p2}) = L(x_{p1}) + L(x_{p2}) = f_1(t) + f_2(t)$$

$$f_1: \alpha = 0$$

$$\beta = 1$$

$$P_n(t) \equiv 1, n=0$$

$$Q_m(t) \equiv 0, m = -\infty \left. \vphantom{\begin{aligned} P_n(t) \equiv 1 \\ Q_m(t) \equiv 0 \end{aligned}} \right\} K=0 \Rightarrow R_0 = c_1, T_0 = c_2$$

$$\alpha \pm i\beta = 0 \pm i = \pm i \Rightarrow \underline{\underline{\delta = 1}} \Rightarrow x_{p1}(t) = t \cdot (c_1 \cos t + c_2 \sin t) \dots a = c = -1/3$$

$$\alpha \pm i\beta = 0 \pm i = \pm i \Rightarrow \underline{\underline{\alpha=1}} \Rightarrow x_{p1}(t) = t \cdot (c_1 \cos t + c_2 \sin t) \dots a=c_2 = -\frac{1}{4}$$

$$f_2: \alpha = 2$$

$$\beta = 0$$

$$P_n(t) \equiv 1 \Rightarrow u = 0$$

$$Q_n(t) = \delta_{uv} \text{ (u=0)} \left. \begin{array}{l} \\ \end{array} \right\} k=0 \Rightarrow R_0(t) \equiv c_1, T_0(t) \equiv c_2$$

$$\alpha \pm i\beta = 2 \pm i0 = 2 \Rightarrow \underline{\underline{\alpha=0}} \Rightarrow x_{p2}(t) = e^{2t} \cdot (c_1 \cos 0t + c_2 \sin 0t) = c_1 e^{2t} \dots a = \frac{4}{5}$$

$$b) x'' - x = \sin 2t$$

$$f(t) = \sin 2t = \frac{1 - \cos 2t}{2} = \frac{1}{2} - \frac{\cos 2t}{2}$$

\swarrow x_{p1} \searrow x_{p2}

$$r) x'' - 4x' + 5x = (\sin t + 2\cos t) \cdot e^{2t}$$

$$\boxed{2 \pm i}$$

$$\alpha = 2$$

$$\beta = 1$$

$$P_n(t) \equiv 2$$

$$Q_n(t) \equiv 1$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} h=u=0 \Rightarrow k=0 \Rightarrow R_0(t) \equiv c_1, T_0(t) = c_2$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} x_p(t) = t \cdot e^{2t} \cdot (c_1 \cos t + c_2 \sin t)$$

$$\alpha \pm i\beta = \boxed{2 \pm i} \Rightarrow \underline{\underline{\alpha=1}}$$

$$d) x'' - 2x' + x = \frac{e^t}{t} \text{ -misi y ovg. odumy } \rightarrow \text{gryzovanye}$$

$$\frac{1}{2}(\lambda-1)^2 = 0$$

$$1,1 \rightsquigarrow e^t, t \cdot e^t$$

$$\text{uqya: } x_p(t) = e^t \cdot g(t)$$

$$x_p'(t) = e^t \cdot g(t) + e^t \cdot g'(t) = e^t (g(t) + g'(t))$$

$$x_p''(t) = e^t (g(t) + g'(t) + g'(t) + g''(t)) = e^t (g(t) + 2g'(t) + g''(t))$$

$$e^t (g'' + 2g' + g) - 2 \cdot e^t (g + g') + e^t g = \frac{e^t}{t} \quad /: e^t$$

$$g'' + 2g' + g - 2g' + g = \frac{1}{t}$$

$$g'' = \frac{1}{t} \Rightarrow g' = \ln|t| + C_1 \Rightarrow g(t) = t \cdot \ln|t| - t + C_1 t + C_2 \left. \begin{array}{l} C_1 = 1 \\ C_2 = 0 \end{array} \right\} g(t) = t \cdot \ln|t|$$

$$x_p(t) = e^t \cdot t \cdot \ln|t|$$

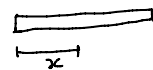
$$\text{OP: } x(t) = C_1 e^t + C_2 t e^t + e^t t \ln|t|, C_i \in \mathbb{R}$$

Парцијалне ДЈ 1. реда

ОДЈ $x(t) \rightarrow$ еволуција у времену, нпр. $\ddot{x} = F$ — II Н. закон

ПДЈ $u(x_1, \dots, x_n) = ? \rightarrow$ еволуција у простору и времену, нпр. $u_t = u_{xx}$
 \downarrow
 јна просторна димензија

$u(t, x)$ — интермитентна функција



t — време

$$\text{Нормална: } u_t = u_t' = \frac{\partial u}{\partial t}$$

$$u_{xx} = u_{xx}'' = \frac{\partial^2 u}{\partial x^2}$$

$$u_{xy}'' = u_{xy}'' = \frac{\partial^2 u}{\partial x \partial y}$$

$$u_t = u_{xx} \rightarrow \text{2. реда}$$

$$\text{1. реда} \rightarrow F(x_1, \dots, x_n, u, \frac{\partial u}{\partial x_1}, \dots, \frac{\partial u}{\partial x_n}) = 0 \rightarrow \text{1. реда}$$

$$\rightarrow \text{Квазилинеарна: } \sum_{j=0}^n a_j(x_1, \dots, x_n, u) \frac{\partial u}{\partial x_j} = c(x_1, \dots, x_n, u)$$

$$\left[\text{линеарна: } \sum_{j=0}^n a_j(x_1, \dots, x_n) \frac{\partial u}{\partial x_j} = c(x_1, \dots, x_n) \right]$$

$$\rightarrow \text{одомбена линеарна: } \sum_{j=0}^n a_j(x_1, \dots, x_n) \frac{\partial u}{\partial x_j} = 0 \quad (c=0)$$

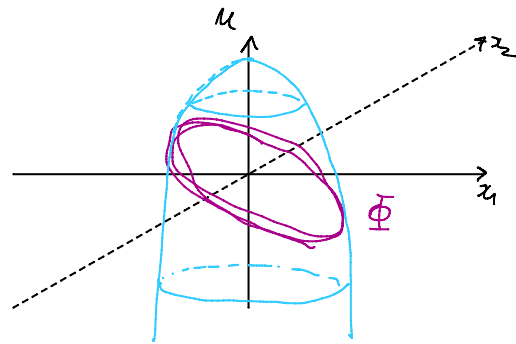
$v \dots \rightarrow 0 \rightarrow z$



$\rightarrow z$

Косинусов продукт: катин решење које садржи некакој функцију Φ .

$$\Phi \in \Gamma(u) \text{ график}$$



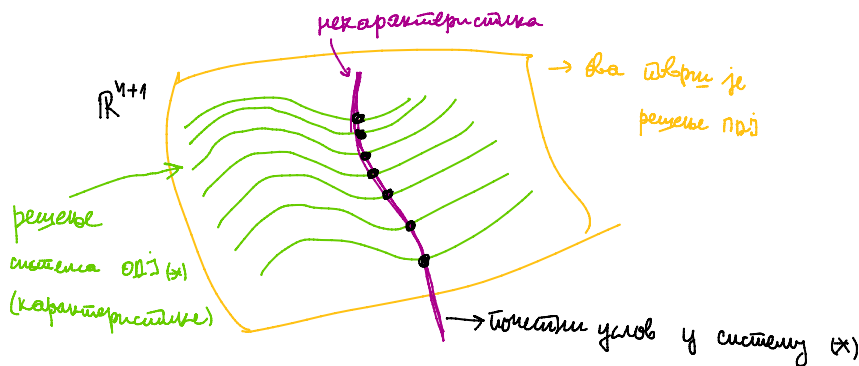
Метода карактеристика

(K1) \Rightarrow систем карактеристика (*)

$$\sum_{j=0}^n a_j(x_1, \dots, x_n, u) \frac{\partial u}{\partial x_j} = c(x_1, \dots, x_n, u) \Rightarrow \left. \begin{aligned} x_j'(t) &= a_j(x_1, \dots, x_n, u), \forall j \\ u'(t) &= c(x_1, \dots, x_n, u) \end{aligned} \right\} (*)$$

(K2) \Rightarrow систем карактеристика (*)

$$\sum_{j=0}^n a_j(x_1, \dots, x_n) \frac{\partial u}{\partial x_j} = 0 \Rightarrow x_j'(t) = a_j(x_1, \dots, x_n), \forall j (*)$$



③ $u'_x + u'_y + 2u = 1 + u^2$, $u(x=0, x=1, x=2) = x$

(K1)

\hookrightarrow косинусов услов

$$\underbrace{1}_{a_1} \cdot u'_x + \underbrace{1}_{a_2} \cdot u'_y = \underbrace{1 - 2u + u^2}_c \Rightarrow \left. \begin{aligned} x'(t) &= 1 \\ y'(t) &= 1 \\ u'(t) &= 1 - 2u + u^2 \end{aligned} \right\}$$

$$x' = 1 \Rightarrow x(t) = t + c_1$$

$$y' = 1 \Rightarrow y(t) = t + c_2$$

$$u' = (1-u)^2 \Rightarrow \frac{u'}{(1-u)^2} = 1 \int$$

$$\int \frac{du}{(1-u)^2} = t + c_3$$

$$\frac{1}{1-u} = t + c_3$$

$$1-u = \frac{1}{t+c_3} \Rightarrow u = 1 - \frac{1}{t+c_3} = \frac{t+c_3-1}{t+c_3}$$

$$u(\underbrace{sm}_{x}, \underbrace{x+x^2}_{y}) = x \rightarrow \text{справд } y \in \mathbb{R}^3$$

$$\delta(t) = (\underbrace{sm}_{x}, \underbrace{x+x^2}_{y}, \underbrace{1}_{u}) \in \Gamma(u) \subseteq \mathbb{R}^3$$

↗ некапонієприсітка

$$c_1, c_2, c_3 \rightarrow c_1(t), c_2(t), c_3(t)$$

$$x(t, t) = t + c_1(t)$$

$$y(t, t) = t + c_2(t)$$

$$u(t, t) = \frac{t + c_3(t) - 1}{t + c_3(t)}$$

початкові умови: $x(0, t) = x_0(t) = sm \cdot t$

$$y(0, t) = y_0(t) = t + t^2$$

$$u(0, t) = u_0(t) = 1$$

$$sm \cdot t = x(0, t) = c_1(t)$$

$$t + t^2 = y(0, t) = c_2(t)$$

$$1 = u(0, t) = \frac{c_3(t) - 1}{c_3(t)} \Rightarrow c_3(t) = c_3(t) - 1 \Rightarrow c_3(t)(1-t) = 1 \Rightarrow c_3(t) = \frac{1}{1-t}$$

вектор (параметризованого шляху — t та u):

$$(x(t, t), y(t, t), u(t, t)) = \left(t + sm \cdot t, t + t + t^2, \frac{t + \frac{1}{1-t}}{t + \frac{1}{1-t}} \right) \checkmark$$