

① Нека је $[a_{ij}]_{i,j=1}^n = A \in M_n(\mathbb{R})$, $a_{ij} \geq 0 \ \forall i \neq j$. Нека је $B = e^A = [b_{ij}]_{i,j=1}^n \in M_n(\mathbb{R})$. Докажи да је $b_{ij} \geq 0 \ \forall i, j$.

$$A = \begin{bmatrix} ? & \geq 0 \\ \geq 0 & ? \end{bmatrix} \rightsquigarrow B = e^A = \begin{bmatrix} \geq 0 \end{bmatrix}$$

$$A = [\geq 0] \rightsquigarrow A^* = [\geq 0] \rightsquigarrow B = e^A = [\geq 0]$$

улога:

$$A = A_1 + E_1$$

$$A_1 - \epsilon_1 \geq 0$$

$$e^{E_1} - \epsilon_1 \geq 0$$

$$\sim A_1 E_1 = E_1 A_1$$

} E_1 - транспонираниа јединица

$$E_1 = -E \cdot \max_{1 \leq i \leq n} |a_{ii}| = M$$

$$A = \begin{bmatrix} -2 & - \\ & 4 & - \\ & & -6 \end{bmatrix}$$

$$M = |-6| = 6$$

$$A_1 = A + 6 \cdot E$$

$$A_1 = \begin{bmatrix} 4 & - \\ & 10 & - \\ & & 0 \end{bmatrix}$$

$$A_1 = A + ME = (A - E_1) \quad (A = A_1 + E_1)$$

$$[c_{ij}]_{i,j=1}^n$$

$$c_{ij} = \begin{cases} a_{ij} \geq 0 & i \neq j \\ a_{ii} + M \geq 0 & i = j \end{cases} \geq 0$$

$$(\forall i) \ a_{ii} + M = a_{ii} + \max_{1 \leq j \leq n} |a_{jj}| \geq a_{ii} + |a_{ii}| \geq 0$$

$$A_1 E_1 = A_1 \cdot (-ME) = -M \cdot (A_1 E) = -M \cdot A_1 = -M \cdot (E A_1) = (-ME) \cdot A_1 = E_1 A_1$$

$$B = e^A = e^{A_1 + E_1} = e^{A_1} \cdot e^{E_1} \Rightarrow b_{ij} \geq 0 \ (\forall i, j)$$

е₁ > 0, јер A₁ има е₁ > 0

е₁ > 0

e^{-M} > 0

$$e^{E_1} = \exp\left(\begin{bmatrix} -M & & \\ & \ddots & \\ & & -M \end{bmatrix}\right) = \begin{bmatrix} e^{-M} & & \\ & \ddots & \\ & & e^{-M} \end{bmatrix}$$

Фундаментални системи решења : скуп и независних решења $\varphi_1(t), \dots, \varphi_n(t)$ система $X'(t) = A(t) \cdot X(t)$ (скуп)

$$\Phi(t) = [\varphi_1(t) \ \dots \ \varphi_n(t)] - \text{фундаментална матрица}$$

$$W(t) = \det \Phi(t) - \text{Вронскијан}$$

⊗ Нека матрица је фундаментална за систем $X' = A(t)X$ $\Leftrightarrow \Phi'(t) = A(t) \cdot \Phi(t)$ и $W(t) \neq 0$ *независна*

$$\begin{bmatrix} \varphi_1'(t) & \dots & \varphi_n'(t) \end{bmatrix} = A(t) \cdot \begin{bmatrix} \varphi_1(t) & \dots & \varphi_n(t) \end{bmatrix}$$

$$\forall i \in \{1, \dots, n\} \quad \varphi_i'(t) = A(t) \cdot \varphi_i(t)$$

$$\otimes \Phi(t) \rightsquigarrow A(t) = \Phi'(t) \cdot \Phi(t)^{-1} \text{ (уносак)}$$

$$X' = AX \rightsquigarrow X = e^{tA} \cdot \underbrace{c}_{c = X(0) = x_0}$$

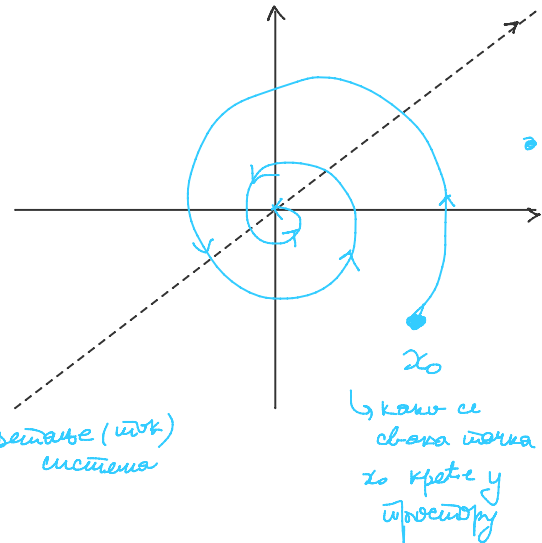
$$X: \mathbb{R} \xrightarrow[t]{\mathbb{R}^n} \mathbb{R}^n$$

$$x_0 \mapsto \underbrace{e^{tA}}_{\text{крива криве}} \cdot x_0$$

$$\Phi_t: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\Phi_t(x_0) = e^{tA} \cdot x_0$$

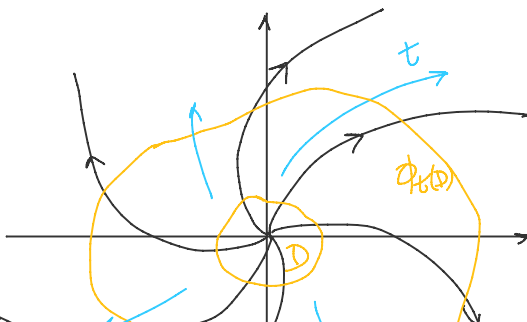
$$\Phi_0 = \text{id}$$



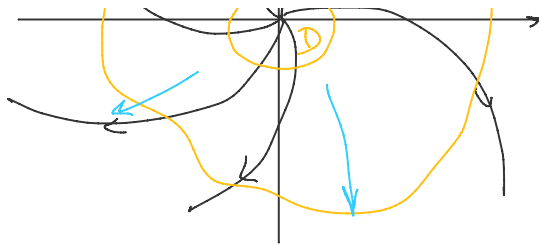
▮ (Лемма) Поку Φ_t система $X' = AX$ може заштитити (непробне) област $D \subseteq \mathbb{R}^n$ као

$$\text{Vol}(\Phi_t(D)) = e^{t \cdot \text{tr} A} \cdot \text{Vol}(D)$$

вп.



$$\text{Vol}(\Phi_t(D)) > \text{Vol}(D) - \text{ubektava zapreminu } t > 0$$



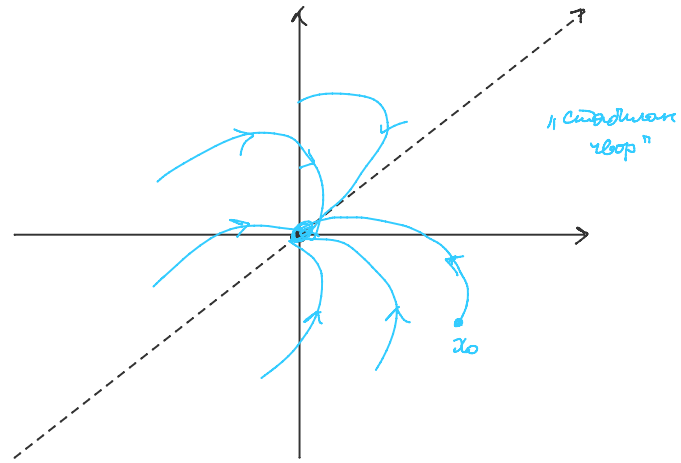
$t > 0$

- маагыже $\text{tr}(A) < 0$
- чыбра $\text{tr}(A) = 0$
- адетабара $\text{tr}(A) > 0$

② $X' = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \lambda_3 \end{bmatrix} X$, $\lambda_3 < \lambda_2 < \lambda_1 < 0$. Како се крете типови режими? Како систем иста стабилност?

$$\Phi_t(x_0) = e^{tA} \cdot x_0 = \begin{bmatrix} e^{\lambda_1 t} & & \\ & e^{\lambda_2 t} & \\ & & e^{\lambda_3 t} \end{bmatrix} \cdot x_0$$

$$\lim_{t \rightarrow +\infty} \Phi_t(x_0) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$



$\text{tr} A = \lambda_1 + \lambda_2 + \lambda_3 < 0 \Rightarrow$ систем маагыже стабилност

③ Докажи дека је сол матрица $X' = AX$ фундаментална матрица гата са $\Phi(t) = e^{tA}$.

1) $\Phi' = A\Phi?$

$$\Phi'(t) = (e^{tA})' \stackrel{(5)}{=} A \cdot \underline{e^{tA}} = A \cdot \Phi(t) \quad \checkmark$$

2) $W(t) = \det(e^{tA}) \stackrel{(6)}{=} e^{\text{tr}(tA)} > 0 \Rightarrow W(t) \neq 0$

$$\text{нпр. } e^{tA} = \begin{bmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{bmatrix}$$

независна переменна система

Решавање нелинеар у одређеном времену

$$X' = AX$$

$$A = P \underbrace{D}_{\text{у Нормановој нормалној форми}} P^{-1}$$

$$X(t) = \underline{e^{tA}} \cdot c = e^{t(PDP^{-1})} \cdot c \stackrel{(*)}{=} P \cdot \underline{e^{tD}} \cdot P^{-1} \cdot c, \quad c \in \mathbb{R}^k$$

e^{tD} - знамо за одређено

P - матрица преласка

\sqrt{A}
 \downarrow
 $D = ?$
 $P = ? (P^{-1}c?)$
 $e^{tD} = ?$

(4)

$$x_1' = x_1 - x_2 + x_3$$

$$x_2' = x_1 + x_2 - x_3$$

$$x_3' = 2x_1 - x_2$$

$$X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad X' = AX, \quad A = \begin{bmatrix} 1 & -1 & 1 \\ 1 & 1 & -1 \\ 2 & -1 & 0 \end{bmatrix}$$

$$\det(A - \lambda E) = 0$$

$$\begin{aligned}
 0 &= \det \begin{pmatrix} 1-\lambda & -1 & 1 \\ 1 & 1-\lambda & -1 \\ 2 & -1 & -\lambda \end{pmatrix} = -2 \cdot (1-\lambda) \cdot 1 - 1 \cdot (-1) \cdot (-\lambda) - (1-\lambda) \cdot (-1)^2 + (1-\lambda)^2 \cdot (-\lambda) + (-1)^2 \cdot 2 + 1^2 \cdot (-1) = \\
 &= -2 + 2\lambda - 1 + \lambda - 1(1-2\lambda+\lambda^2) + 2 - 1 = \\
 &= 2\lambda - 2 - \lambda + 2\lambda^2 - \lambda^3 = -\lambda^3 + 2\lambda^2 + \lambda - 2 = \\
 &= (\lambda-1)(-\lambda^2 + \lambda + 2) = \\
 &= (\lambda-1)(\lambda+1)(2-\lambda)
 \end{aligned}$$

$$\left. \begin{array}{l} \lambda_1 = 1 \\ \lambda_2 = -1 \\ \lambda_3 = 2 \end{array} \right\} \text{ три с. вр. су реалне и различите} \rightarrow 3 \text{ с. вр. век.}$$

$$\lambda_1 = 1: (A - \lambda_1 E) \delta_1 = 0$$

$$\begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ 2 & -1 & -1 \end{bmatrix} \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0$$

$$\begin{array}{l} -b + c = 0 \\ a - c = 0 \\ 2a - b - c = 0 \end{array} \left\{ \begin{array}{l} \downarrow + \\ \leftarrow + \end{array} \right.$$

$$\begin{array}{l} -b + c = 0 \\ a - b = 0 \\ 2a - 2b = 0 \end{array} \left\{ \begin{array}{l} c = b = a \\ \uparrow \\ a = b \end{array} \right.$$

$$\Rightarrow \delta_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = -1: (A - \lambda_2 E) \delta_2 = 0$$

$$\dots \dots \dots \quad [1]$$

$$\lambda_2 = -1: (A - \lambda_2 E) \mathbf{k}_2 = 0$$

$$(A + E) \mathbf{k}_2 = 0 \Rightarrow \mathbf{k}_2 = \begin{bmatrix} 1 \\ -3 \\ -5 \end{bmatrix}$$

$$\lambda_3 = 2: (A - \lambda_3 E) \mathbf{k}_3 = 0 \Rightarrow \mathbf{k}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$P = \begin{bmatrix} \mathbf{k}_1 \downarrow & \mathbf{k}_2 \downarrow & \mathbf{k}_3 \downarrow \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -3 & 0 \\ 1 & -5 & 1 \end{bmatrix}$$

$$D = \begin{bmatrix} 1 & & \\ & -1 & \\ & & 2 \end{bmatrix} \Rightarrow e^{tD} = \begin{bmatrix} e^t & & \\ & e^{-t} & \\ & & e^{2t} \end{bmatrix}$$

$$P^{-1} = ? \quad P^{-1} = \frac{1}{\det P} \cdot \text{Adj} P = \frac{1}{-6} \cdot \begin{bmatrix} + \begin{vmatrix} -3 & 0 \\ -5 & 1 \end{vmatrix} & - \begin{vmatrix} 1 & 0 \\ 1 & 1 \end{vmatrix} & + \begin{vmatrix} 1 & -3 \\ 1 & -5 \end{vmatrix} \\ - \begin{vmatrix} 1 & 1 \\ -5 & 1 \end{vmatrix} & + \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} & - \begin{vmatrix} 1 & 1 \\ 1 & -5 \end{vmatrix} \\ + \begin{vmatrix} 1 & 1 \\ 1 & -3 \end{vmatrix} & - \begin{vmatrix} 1 & 1 \\ 1 & 0 \end{vmatrix} & + \begin{vmatrix} 1 & 1 \\ 1 & -3 \end{vmatrix} \end{bmatrix}^T = \frac{1}{-6} \begin{bmatrix} 3 & -1 & -2 \\ -6 & 0 & 6 \\ 3 & 1 & -4 \end{bmatrix}^T = \frac{1}{6} \begin{bmatrix} 3 & 6 & -3 \\ 1 & 0 & -1 \\ 2 & -6 & 4 \end{bmatrix}$$

$$\det P = -3 + 0 - 5 + 3 - 0 - 1 = -6$$

$$\text{op: } X(t) = P e^{tD} P^{-1} \cdot c = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -3 & 0 \\ 1 & -5 & 1 \end{bmatrix} \cdot \begin{bmatrix} e^t & & \\ & e^{-t} & \\ & & e^{2t} \end{bmatrix} \cdot \frac{1}{6} \begin{bmatrix} 3 & 6 & -3 \\ 1 & 0 & -1 \\ 2 & -6 & 4 \end{bmatrix} \cdot c, c \in \mathbb{R}^3$$

$$= P \cdot e^{tD} \cdot c_1, c_1 \in \mathbb{R}^3 \quad (* \text{ mome u des } P^{-1} \text{ ako ne upreza!})$$

$$\textcircled{5} \quad x_1' = -3x_1$$

$$x_2' = 3x_2 - 2x_3$$

$$x_3' = x_2 + x_3$$

$$A = \begin{bmatrix} -3 & 0 & 0 \\ 0 & 3 & -2 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\det(A - \lambda E) = 0 \Rightarrow \dots -(\lambda + 3)(\lambda^2 - 4\lambda + 5) = 0$$

$$\lambda_1 = -3$$

$$\lambda_2 = 2 + i \quad \text{konjug. konj.}$$

$$\lambda_3 = 2 - i$$

$$\lambda_1 = -3, (A - \lambda_1 E) \vec{v}_1 = 0 \dots \Rightarrow \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\lambda_2 = 2+i:$$

$$(A - \lambda_2 E) \vec{v}_2 = 0$$

$$\begin{bmatrix} -3-(2+i) & 0 & 0 \\ 0 & 3-(2+i) & -2 \\ 0 & 1 & 1-(2+i) \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0$$

$$(-5-i)a = 0 \Rightarrow a = 0$$

$$(1-i)b - 2c = 0 \Rightarrow c = \frac{1-i}{2} \cdot b$$

$$\left. \begin{array}{l} b + (-1-i)c = 0 \\ \hookrightarrow \cdot (1-i) \end{array} \right\} (1-i)b - \underbrace{(1+i)(1-i)}_{-2} c = 0$$

$$\vec{v}_2 = \begin{bmatrix} 0 \\ 1+i \\ 1 \end{bmatrix}$$

$$\begin{array}{l} b = 1+i \\ \Rightarrow c = 1 \end{array}$$

$$D = \begin{bmatrix} \boxed{-3} & 0 & 0 \\ 0 & \boxed{2 \ 1} \\ 0 & \boxed{-1 \ 2} \end{bmatrix} \begin{array}{l} \lambda_1 = -3 \\ \lambda_2 = 2+i \\ 2 \times 2 \end{array}$$

$$\alpha + i\beta \leftrightarrow \begin{bmatrix} \alpha & \beta \\ -\beta & \alpha \end{bmatrix}$$

$$\lambda_2 = 2+i \leftrightarrow \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix} \begin{array}{l} \alpha = 2 \\ \beta = 1 \end{array}$$

$$e^{tD} = \begin{bmatrix} e^{-3t} & 0 & 0 \\ 0 & \boxed{\exp(t \begin{bmatrix} 2 & 1 \\ -1 & 2 \end{bmatrix})} \\ 0 & & \end{bmatrix} = \begin{bmatrix} e^{-3t} & 0 & 0 \\ 0 & \boxed{\begin{matrix} e^{2t} \cos t & e^{2t} \sin t \\ -e^{2t} \sin t & e^{2t} \cos t \end{matrix}} \end{bmatrix}$$

(1) - *длина*
 $e^{2t} \cdot R(1+t)$

√ блок матриц:

$$D = \begin{bmatrix} \boxed{B_1} & \\ & \boxed{B_2} \end{bmatrix}$$

$$e^{tD} = \begin{bmatrix} \boxed{e^{tB_1}} & \\ & \boxed{e^{tB_2}} \end{bmatrix}$$

$$P = \begin{bmatrix} \vec{v}_1 \downarrow & \text{Re} \vec{v}_2 \downarrow & \text{Im} \vec{v}_2 \downarrow \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} 0 \\ 1+i \\ 1 \end{bmatrix} \Rightarrow \text{Re} \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$\text{Im} \vec{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\sqrt{\text{за бевдэ: } P^{-1} = \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & -2 \end{bmatrix}}$$

$$\text{OP: } X(t) = P \cdot e^{tD} \cdot \underbrace{c}_{P^{-1} \cdot \bar{c}}, c \in \mathbb{R}^3$$